

# **Sub-nanosecond GPS Time Transfer; Global Solutions Using Carrier Phase and Pseudorange**

**L. E. Young, C. E. Dunn,  
S. L. Lichten and D. C. Jefferson  
California Institute of Technology,  
Jet Propulsion Laboratory**

**ley@jpl.nasa.gov  
(81 8) 354-5018**

**1995 IEEE International Frequency Control Symposium  
San Francisco, California, USA  
May 31-June 2, 1995**



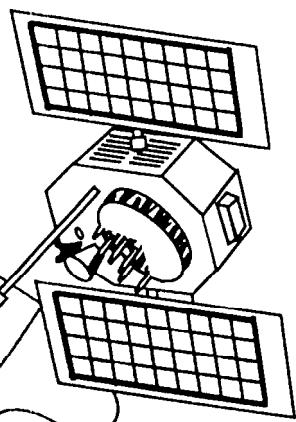
## **Sub-nanosecond GPS Time Transfer**

### **Outline**

- o Precise time transfer at JPL (*a partial history*)
  - o VLBI
  - o Common view GPS
  - o Global solution GPS ( The topic of this talk)
- o GPS signal. Information content in pseudorange and carrier phase.
- o Global solution approach and errors
- o Results
- o Future prospects

# GPS Signal Structure

## GPS Satellite



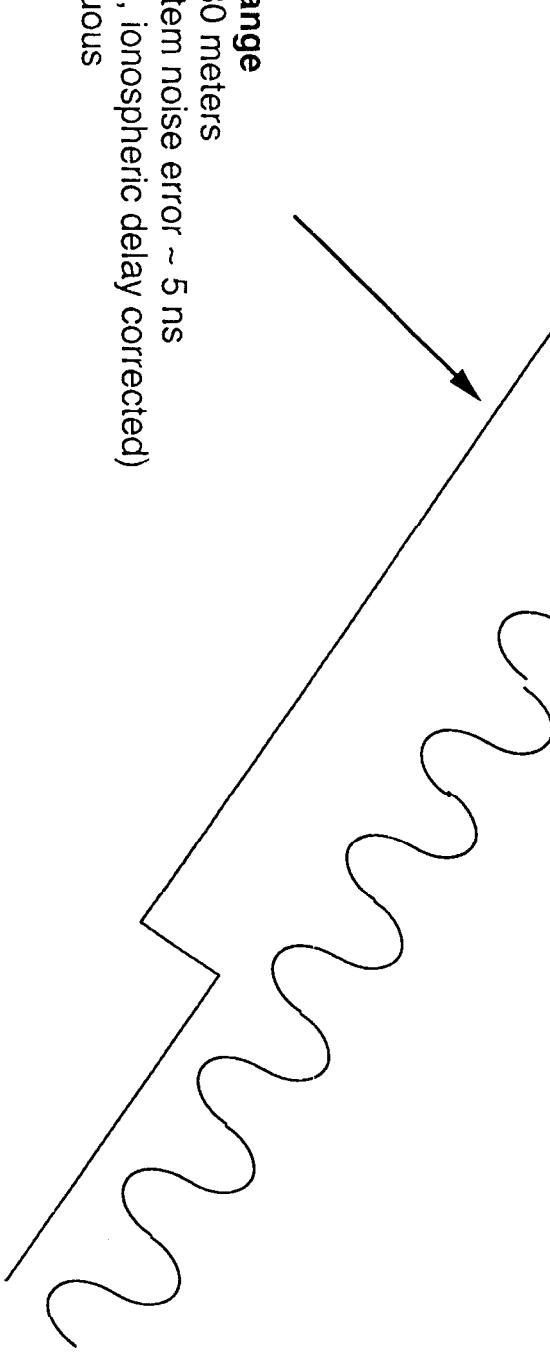
### Carrier phase

Not to scale, one P chip is  
really 154 carrier cycles,  
one C/A chip is 1540 carrier  
cycles

1 cycle ~ 190/244 mm for L1/L2 frequency  
1 sec system noise error ~ 0.025 ns  
(codeless, ionospheric delay corrected)  
Unknown bias of n cycles

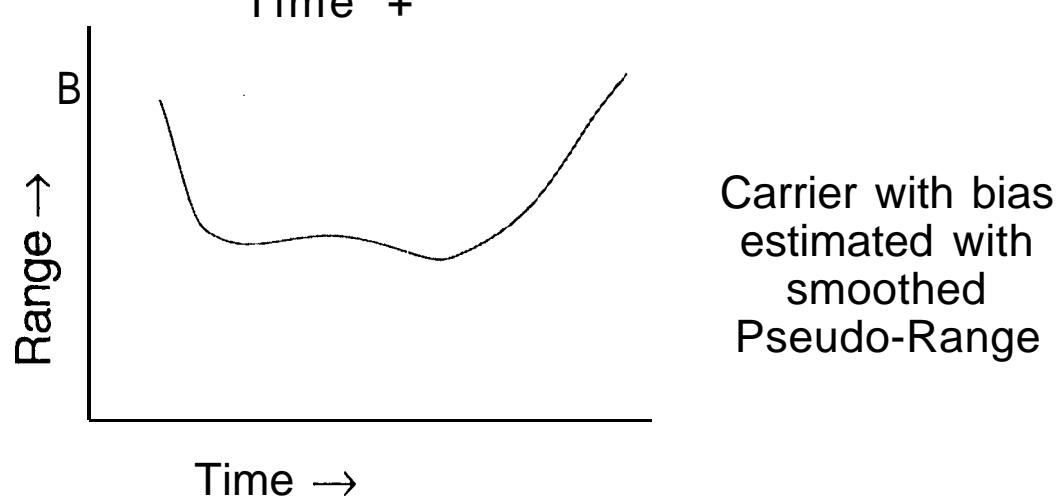
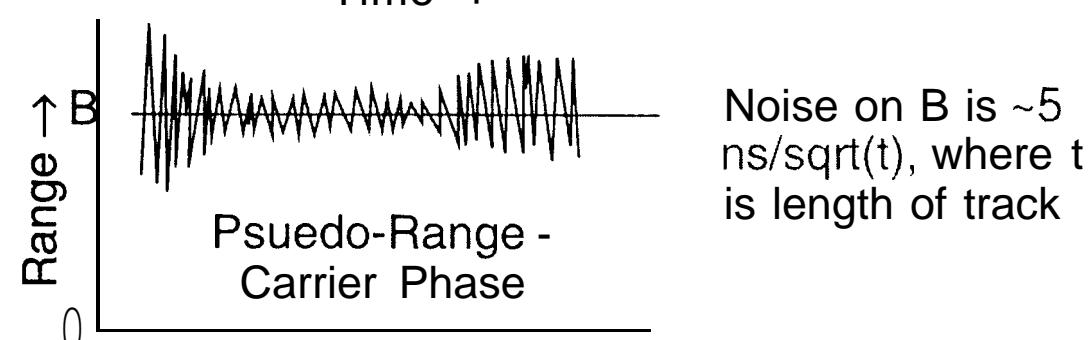
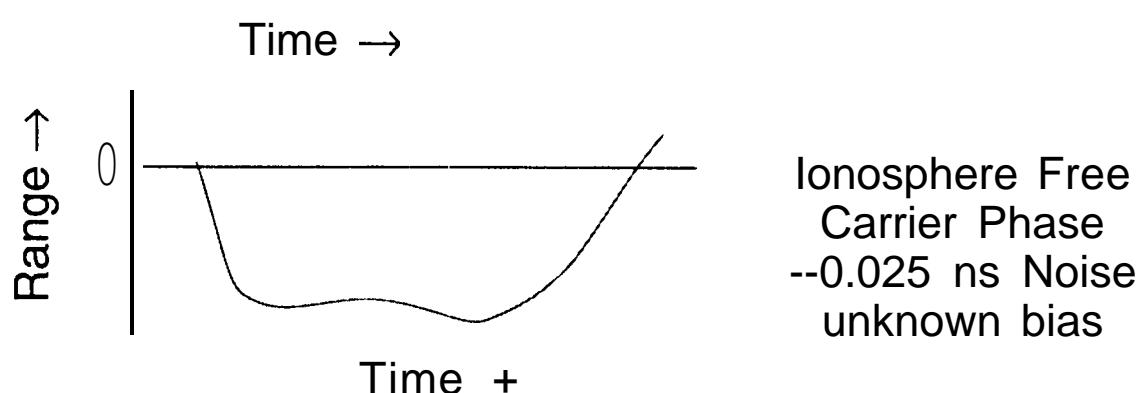
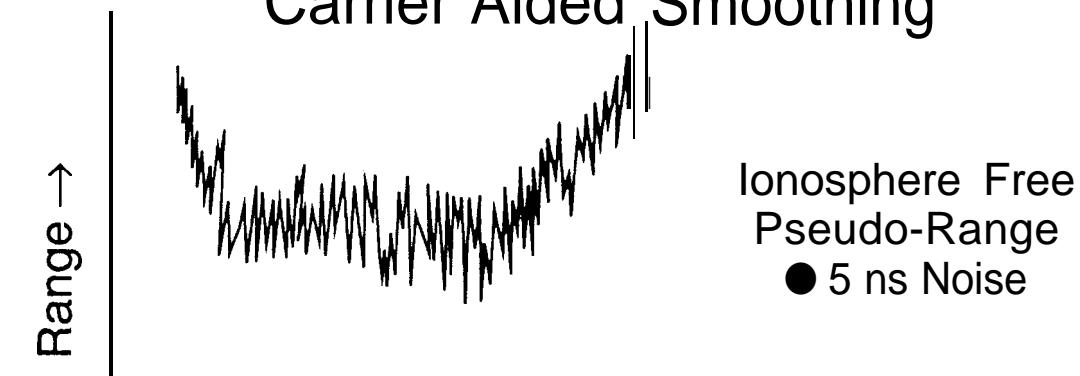
### Pseudorange

1 chip ~ 30 meters  
1 sec system noise error ~ 5 ns  
(codeless, ionospheric delay corrected)  
Unambiguous

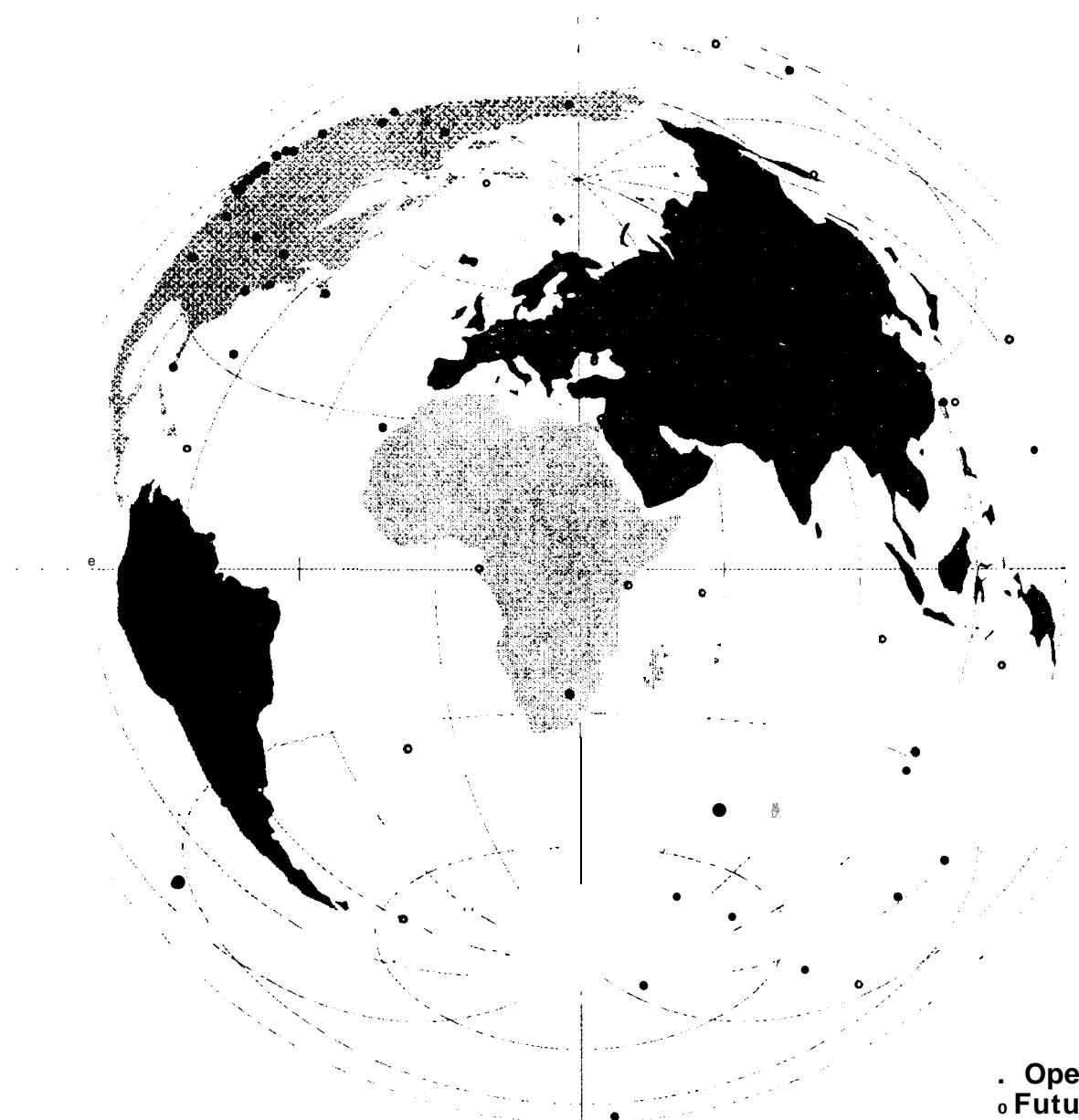


# Global GPS Solution

## Carrier Aided Smoothing



# IGS STATIONS

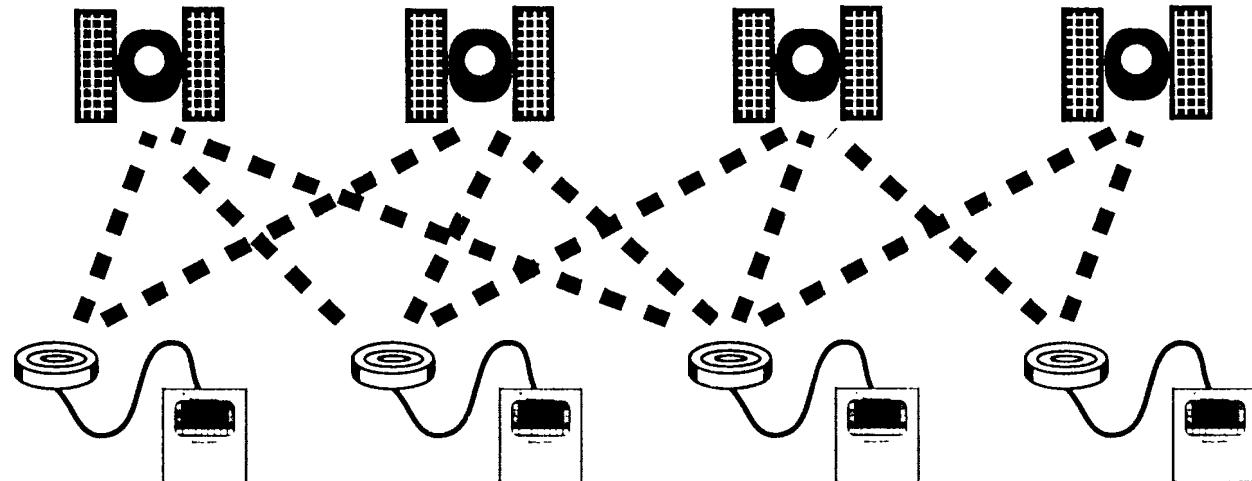


*March 1995*

# Global GPS Solution

## Estimation Strategy

- ☛ Common GPS Satellites are tracked by **-35** Ground Sites.
- ☛ Sub-ns clock sync obtained between sites with no common view



- ☛ This allows simultaneous solutions of:

- Satellite Ephemerides & Clocks (white noise)
- Ground Positions & Clocks (white noise)
- Random Walk Tropospheric Delays
- Earth Orientation
- Solar Radiation Pressure
- -1,500 non-clock parameters each day
- ~ 22,000 station and satellite clock parameters
- using -100,000 measurements/day

- ☛ Calibrated effects include:

- General & Special Relativity
- Ionospheric Delay

# Global GPS Solution

## Estimation Strategy (contd)

☞ Measurement precision is 0.01 ns every 5 minutes.

☞ Error sources:

- Noise
- Signal Multipath
- Orbit Error
- Uncalibrated Troposphere Delay
- Ionosphere Calibration Error
- Variations in instrumental delay

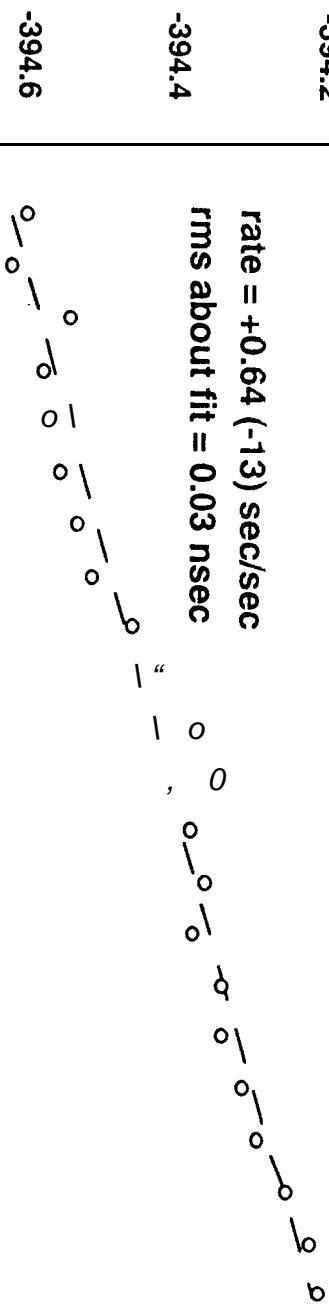
☞ Inferred Time Transfer Error: 100-200 ps  
(Intercontinental distances, 30 hour segments)

# Global GPS Solution (0.030 ns clock offset precision)

## Measurement of DSN Clocks with GPS

Canberra-Goldstone

rate = +0.64 (-13) sec/sec  
rms about fit = 0.03 nsec



Clock offset (nsec)

-394.0

-394.2

22

22.5

23

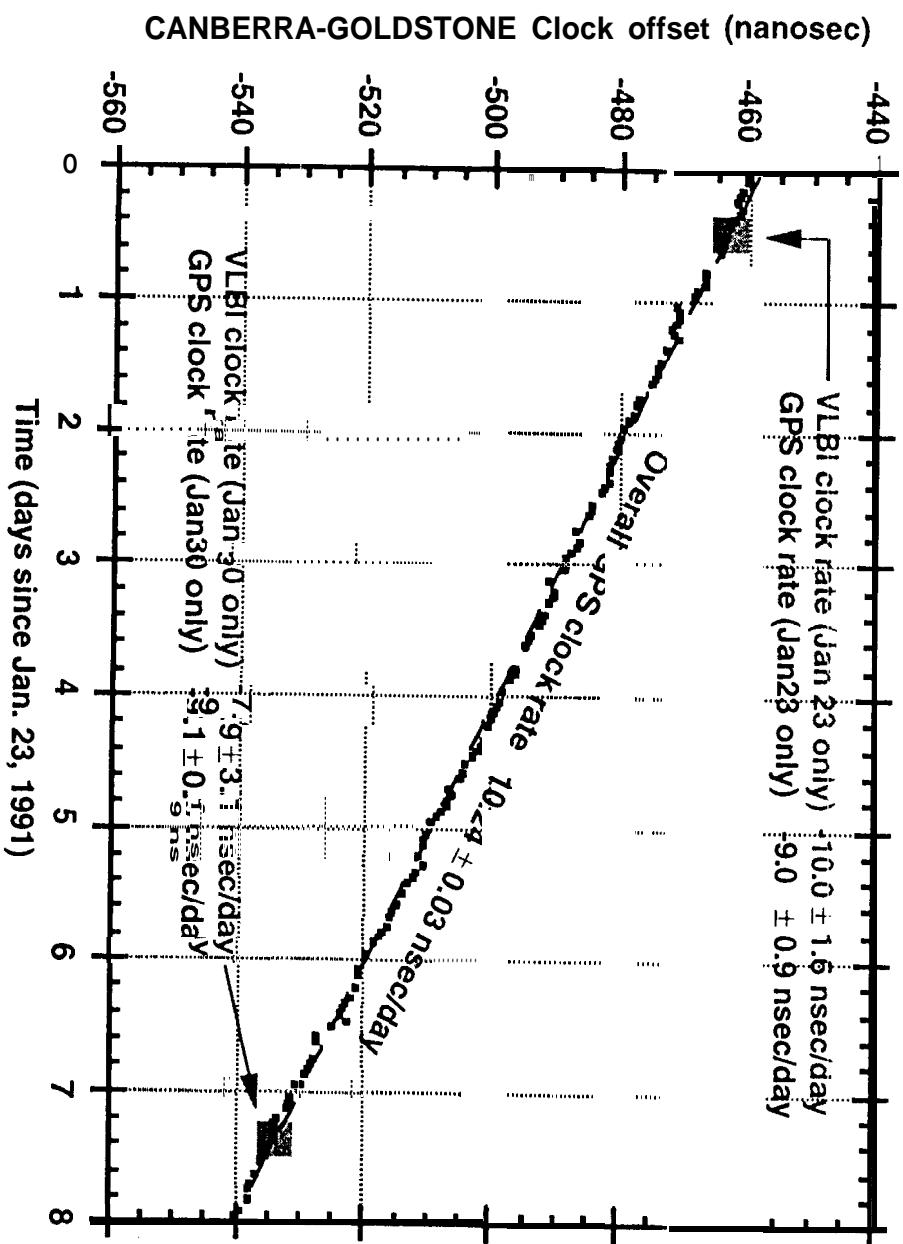
23.5

24

Time Sep 22 1992 (UTC hrs)

# Global GPS Solution ( $3.5 \times 10^{-16}$ clock rate precision)

## GPS DSN Clock Offset Determination



- o Status summary
- o Short-term precision of GPS time transfer over intercontinental distances is about 30 picoseconds
- o GPS time transfer over one week can measure clock rates to a few parts in  $10^{-16}$
- o Future prospects for improvements in GPS time transfer
- o Improved antennas and receivers to reduce multipath errors.
- o Improved models/estimation of media delays.
- o Improved GPS dynamic models (altitude, solar pressure, ..) will lead to more accurate orbits.
- o Combined GPS/GLONASS time transfer.
- o Enhancements to the GPS satellites
- o Autonav (with formation of tightly coupled ensemble of satellite clocks)
- o Reduction or elimination of SA
- o Second frequency with non-encrypted code
- o Better clocks on satellites
- o Additional satellites, perhaps in GEO or LEO
- o Realtime differential systems such as WAAS

## Sub-nanosecond GPS Time Transfer

## Status & Future Prospects

